

LM 2100 Payload Accommodation

INTRODUCTION

Lockheed Martin Space encourages payload providers and mission planners to create missions optimized for—or at least compatible with—our versatile and highly capable LM 2100 geosynchronous-orbiting (GEO) platform. The table below provides a summary of typical interfaces and performance capabilities provided by the LM 2100 platform. These specifications serve only as a guide to those interested in flying on this bus. An actual compatibility assessment is best done through an exchange of detailed information and interface requirements. In many cases, specific interface adaptations can be easily created.

Likewise, Figures 1 and 2 provide notional examples of payloads and where they might be accommodated on an LM 2100-based satellite. Figures 3 and 4 provide specific definition of the volumes available for payload mounting based on typical launch vehicle fairing constraints.

Table 1. LM 2100 Hosted Payload Accommodation

| Nominal Payload Resource Allocations | |
|---|---|
| Payload Mass Limit | 1000 kg |
| Payload Power | 12000 W |
| Payload Thermal Dissipation | 6000 W |
| Payload Volume (contiguous) | 3.5 m ³ |
| , , , | |
| Key Platform Performance Characteristics | |
| Attitude Control (Including Stationkeeping Maneu | vers) |
| Attitude Control System | 3-axis stabilized, zero momentum bias |
| Pointing Knowledge, 3σ | 0.02° Roll/Yaw/Pitch |
| Total Pointing Accuracy, 3σ | 0.10° Roll/Yaw/Pitch (optional 0.03° per axis) |
| Acceleration Environment (Jitter) | <20 milli-g with optional vibration isolation |
| Mission Parameters | 25 mm & man optional ribitation isolation |
| Orbit | GEO: 35786 km circular, longitude/inclination maintained ± 0.05° |
| Duration | 15 years |
| Probability of Success | >0.80 for 15 year mission |
| Nominal Program Schedule | 18-36 mo |
| | |
| Key Platform Interface Characteristics | |
| Command and Data Handling Interfaces | |
| Main Data bus | MIL-STD-1553B data bus |
| Alternate Serial Bus Interface | RS-422 derived bi-directional serial bus |
| Pulse Commands | -32 V, 28V |
| Telemetry Types available | Active analog, passive analog, discrete, serial (bidirectional serial |
| Payload Downlink | bus), serial (1553), software 16 Bit / 32 Bit words, and memory dump |
| | No specific constraints. Data rates 10 kbps to 100 Mbps and above |
| | are readily accommodated. |
| Power | |
| Main Bus Voltage (Standard) | 70 V Regulated to 68 V to 71 V |
| Secondary Bus Voltage (Optional) | 28 V Regulated to ± 2V |
| Vibration | |
| Standard Component Random Vibration | 0.2 G ² /Hz 20-1000 Hz |
| Environment | -6 dB/Oct 1000-2000 Hz |
| Standard Component Sine Vibration Environment | 0.5" D.A. 10-24 Hz |
| | 15.0 G 24-35 Hz |
| | 20.0 G 36-55 Hz |
| The survey of | 7.0 G 56-100 Hz |
| Thermal | L L O 1612 To 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 |
| Internal Temperature Environments | In-Orbit Temperature Range -24°C and +61°C |
| Construct The soul Desire Criteria | Transfer Orbit Temperature Range -24°C and +30°C |
| Component Thermal Design Criteria | Maximum average baseplate temperature 45°C; ±15°C max diurnal |
| Baliability / Commissability / Flacture magnetic Course | swing. |
| Reliability / Survivability / Electromagnetic Compa | • |
| Radiation Tolerance | 20-100 kRad(Si) Total Dose |
| Single Event Effects | <1 critical upset per box per 1000 yr >20 dB (200 MHz to 40 GHz) |
| Payload Module Shielding Effectiveness | |

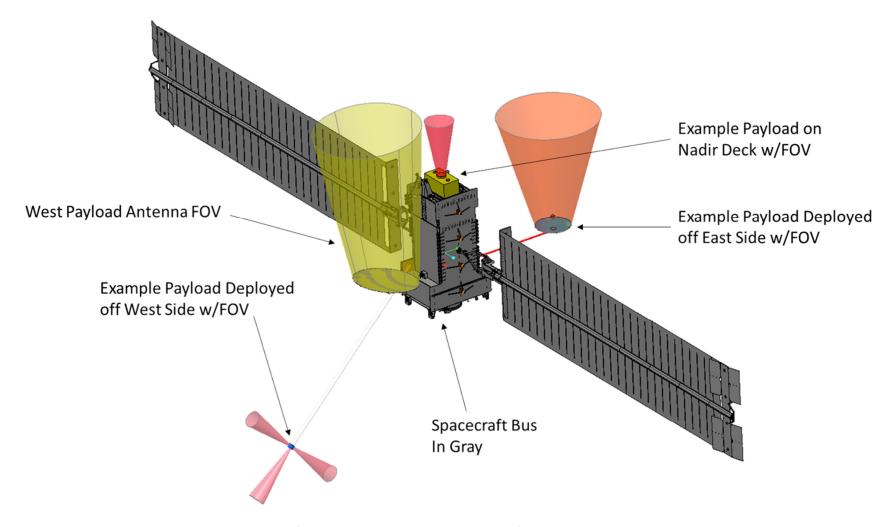


Figure 1. External view of typical LM 2100 showing a variety of potential payload mounting locations

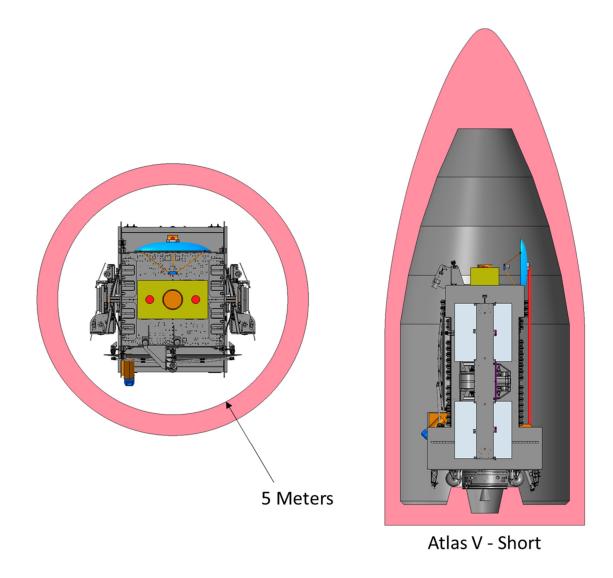


Figure 2. Typical LM 2100 showing size constraints when mounted in typical launch vehicle fairings. Falcon 9 also available

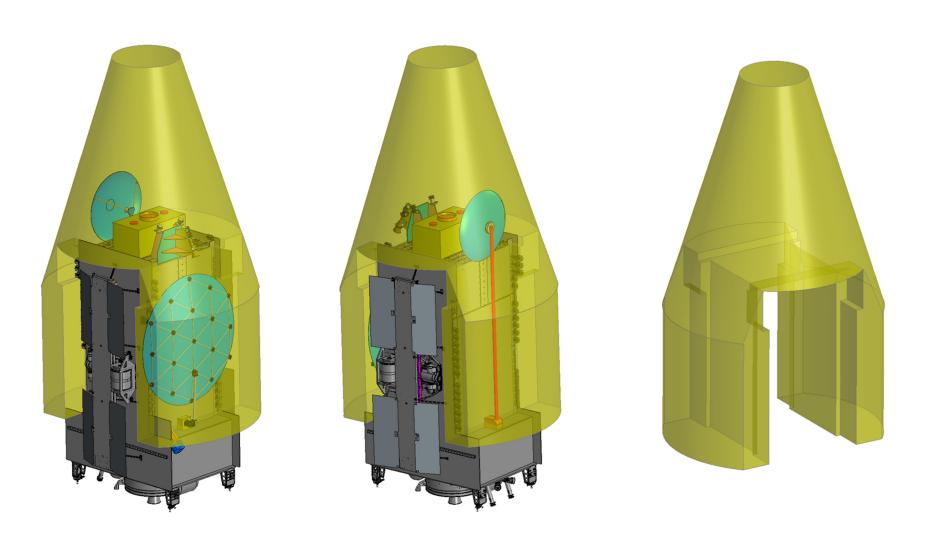


Figure 3. Volume available for payload mounting on LM 2100

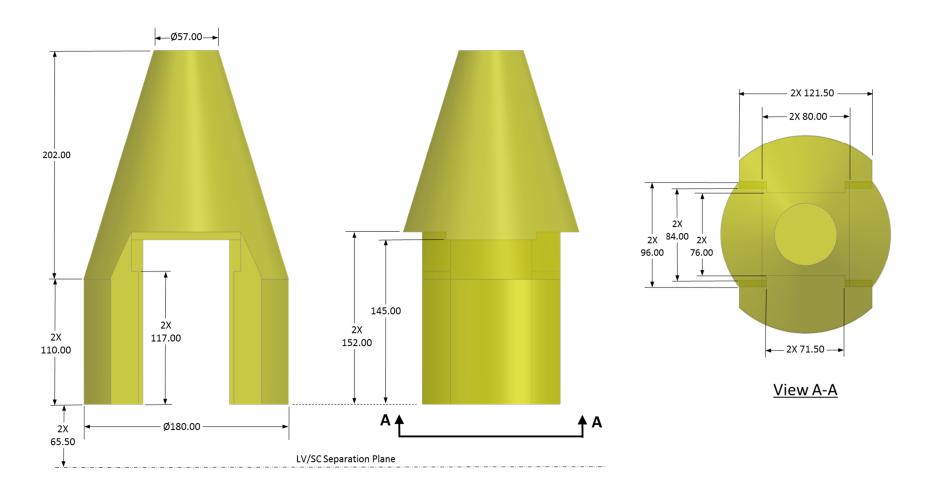


Figure 4. Volume available for payload mounting on LM 2100 with dimensions in inches